

M-3iA/6S



Max. load capacity at wrist: 6 kg



Max. reach: 1350 mm

FANUC

| Robot | | | Max. load capacity at wrist (kg) | Reach (mm) | Controlled axes | Repeatability (mm) | Mechanical weight (kg) | Motion range (°) | | | | | | Maximum speed (°/s) | | | | | | J4 Moment/ Inertia | J5 Moment/ Inertia | J6 Moment/ Inertia | Average Power consumption (kW) | Protection | |
|--------|---------|------|----------------------------------|------------|-----------------|--------------------|------------------------|------------------------------|----|----|-----|----|----|---------------------|----|---------------------------|----|----|-----|--------------------|--------------------|--------------------|--------------------------------|------------|----------------|
| Series | Version | Type | | | | | | J1 | J2 | J3 | J4 | J5 | J6 | J1 | J2 | J3 | J4 | J5 | J6 | | | | | Body | Wrist & J3 arm |
| M-3 | iA | 6S | 6/8 ^(*5) | 1350 | 4 | ± 0.1 | 160 | ∅ 1350 X 500 ^(*3) | | | 720 | - | - | - | - | 4000/2000 ^(*5) | - | - | *4) | NA | 2.5 | IP67 | IP67 | | |

● standard ○ on request - not available () with hardware and/or software option *3) ∅ in mm by height in mm *4) refer to the wrist load diagram *5) high-inertia option

M-3iA/6S 4-axis, hollow wrist



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