

# M-410iB/140H



Max. load capacity  
at wrist: 140 kg



Max. reach:  
2850 mm

# FANUC

Robot			Max.load capacity at wrist (kg)	Reach (mm)	Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						Moments (N-m)/Inertia (kg-m <sup>2</sup> )			Protection		
Series	Version	Type						J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6	J4 Moment/ Inertia	J5 Moment/ Inertia	J6 Moment/ Inertia	Average Power consumption (kW)	Body standard/optional	Wrist & J3 arm standard/optional
M-410	iB	140H	140	2850	5	± 0.05*	1200	360	155	112	20**	720	-	140	115	135	135	420	-	147	53	-	3	IP54	IP54

● standard ○ on request - not available \* Based on ISO9283 \*\*J4 can travel +/- 10 degrees away from the horizontal plane (the horizontal plane is where the faceplate points straight downwards)

M-410iB/140H

5-axis



M-410iB/140H

